

#4: LONGITUDINAL + OFF-MOMENTUM MOTION 1/22/19

$$\begin{pmatrix} x \\ x' \\ y \\ y' \\ z \\ \delta \end{pmatrix}$$

$$\delta = \frac{\Delta p}{p} \neq 0$$

Q: Why do we need (non linear) sextupoles?

CONSTANT MOMENTUM OFFSET

$$f = \frac{p - p_0}{p} = \frac{\Delta p}{p}$$

Recall Hill's eq valid only: for betatron oscillations.

$$\begin{aligned}x'' + k(s) \cdot x &= 0 \\y'' - k(s) \cdot y &= 0\end{aligned}$$

Quad strength k is periodic in s

$$k(s) = k(s + C)$$

$$0 \leq s < C$$

Bending radius R in a dipole becomes

$$\frac{1}{R} = \frac{1}{\rho} \cdot \frac{1}{(1+\delta)} = \underbrace{G}_{1/\rho} \cdot \frac{1}{(1+\delta)}$$

The TOTAL bend accumulated in a slice Δs is

$$\Delta X_{TOT} = G \left(1 - \frac{1}{1+\delta} \right) \Delta s$$

Thanks to the rotating co-ordinate frame

Introduce TOT here: e.g.

$$X_{TOT} = \underbrace{x(s)}_{\text{CLOSED ORBIT}} + \underbrace{X}_{\text{BETATRON OSCILLATIONS}}$$

Adding in quadrupoles of strength $\frac{k}{1+d}$

GENERALISED HILL'S EQNS:

$$\begin{aligned}x''_{TOT} + \frac{k}{1+d} x_{TOT} &= G \left(1 - \frac{1}{1+d}\right) \\y''_{TOT} - \frac{k}{1+d} y_{TOT} &= 0\end{aligned}$$

- Assuming no vertical bending dipoles
- These equations are EXACT to all orders in δ
- $k(s)$ & $G(s)$ are periodic in s

To first order in δ :

(A)

$$x_{TOT}'' + k(1-\delta)x_{TOT} \approx G \cdot \delta$$

$$y_{TOT}'' - k(1-\delta)y_{TOT} = 0$$

DISPERSION FUNCTION

η

(B)

$$x_{TOT} = \underbrace{\eta(s) \cdot \delta}_{\text{closed orbit}} + x$$

closed orbit

betatron osc.

Closed orbit (dispersion) respects Periodic Boundary Conditions (PBC)

Strictly speaking dispersion is a polynomial

$$\eta(s) = \eta_0(s) + \eta_1(s) \cdot \delta + \eta_2 \delta^2 + \dots$$

usually we only care about $\eta = \eta_0$

Substitute (B) into (A) to get:

$$\eta'' + K\eta = G$$

First order dispersion
with PBC

AND

$$\begin{aligned} x'' + \frac{K}{(1+\delta)} x &= 0 \\ y'' - \frac{K}{(1+\delta)} y &= 0 \end{aligned}$$

BETATRON
OSCILLATIONS

Weaker/stronger quadr perturb $\beta(\delta)$, $Q(\delta)$, ...

REVERT B MATRICES

$$\begin{pmatrix} x \\ \dot{x} \\ y \\ \dot{y} \\ z \\ \dot{z} \end{pmatrix} = A(6 \times 6) \begin{pmatrix} \end{pmatrix} \quad 6-$$

In a long dipole with
 $L = P\theta$ (and $k=0$)

$$y'' = G = \frac{1}{P}$$

So $\begin{pmatrix} M \\ y' \\ 1 \end{pmatrix}_{OUT} = \begin{pmatrix} 1 & L & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} P(1 - \cos(\theta)) \\ \sin(\theta) \\ 1 \end{pmatrix} \begin{pmatrix} M \\ y' \\ 1 \end{pmatrix}_{IN}$

OR in general

$$\begin{pmatrix} M \\ y' \\ 1 \end{pmatrix}_2 = \begin{pmatrix} m_{11} & m_{12} & m_{16} \\ m_{21} & m_{22} & m_{26} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} M \\ y' \\ 1 \end{pmatrix}_1$$

EG 1: M is a one-turn 3×3 matrix

$$\begin{pmatrix} \mu \\ \mu' \\ 1 \end{pmatrix} = M \begin{pmatrix} \mu \\ \mu' \\ 1 \end{pmatrix}$$

is easily solved for (μ, μ') at the reference point.

EG 2: From thin quadrupole D (center) to F (center) in a FODO cell

$$\begin{pmatrix} \mu \\ \mu' \\ 1 \end{pmatrix}_F = \begin{pmatrix} 1 & 0 & 0 \\ -q & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & L & \frac{1}{2}L\theta \\ 0 & 1 & \theta \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ q & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \mu \\ \mu' \\ 1 \end{pmatrix}_D$$

with $\mu'_F = \mu'_D = 0$ (matched periodic solution)

and so

$$\begin{aligned} \mu_{\text{MAX}} &= LG \left(\frac{2+s}{2s^2} \right) \\ \mu_{\text{MIN}} &= LG \left(\frac{2-s}{2s^2} \right) \end{aligned}$$

$$\sim \frac{L^2}{\rho}$$

where

$$s \equiv \sin \left(\frac{\Delta\phi}{2} \right) = |qL|$$

OSCILLATING MMTM / LONGITUDINAL MOTION

Q: A particle with $\delta > 0$ goes faster, $S \neq \text{CONST}$
but travels further: which wins?
(Clue: is $\delta \gg 1$)

PATH LENGTH (1 turn closed orbit)

increases by

$$\Delta C_{\text{PATH}} = \oint \eta \cdot d\theta$$

since

$$\frac{d\theta}{ds} = \frac{1}{\rho}$$

$$\Delta C_{\text{PATH}} = \oint \frac{\eta}{\rho} \cdot ds$$

Moves towards
back of
bunch

HIGHER SPEED MOVES FORWARD (per turn) by

$$\Delta C_{\text{SPEED}} = C \frac{\Delta \beta}{\beta} = C \frac{\delta}{\gamma^2}$$

Adding the 2 effects together:

$$\textcircled{A} \quad z_{n+1} = z_n - \eta_s \cdot \delta_n$$

where SLIP FACTOR \rightarrow (COMPACTION FACTOR)

$$\eta_s \equiv \frac{1}{\gamma_T^2} - \frac{1}{\gamma^2}$$

$$\frac{1}{\gamma_T^2} \equiv \frac{1}{C} \int \frac{M}{\rho} ds$$

$$\text{Is } \gamma > \gamma_T$$

HOW DOES S_n CHANGE?

Going through an RF cavity ENERGY changes:

$$E_{n+1} = E_n + qV_{RF} \cdot \sin\left(2\pi \frac{z_n}{\lambda_{RF}}\right)$$

where

$$f_{RF} = \frac{c}{\lambda_{RF}} = h f_{REV}$$

↑
INTEGER HARMONIC NUMBER

and

$$\frac{\Delta p}{p_0} = \frac{1}{\beta^2} \frac{\Delta E}{E_0}$$

(B)

$$S_{n+1} = S_n + \left(\frac{qV_{RF}}{\beta^2 E_0} \right) \cdot \sin\left(2\pi \frac{z_n}{\lambda_{RF}}\right)$$

FOR SMALL OSCILLATIONS

$$|z| \ll \lambda_{RF}$$

$$z_{n+1} = z_n - (m_s c) \cdot \delta_n$$

$$\delta_{n+1} \approx \delta_n + \left(\frac{q V_{RF}}{\beta^2 E_0} \right) \left(\frac{2\pi}{\lambda_{RF}} \right) \cdot z_{n+1}$$

$$\begin{aligned} z_n &= a_z \sin \left(2\pi Q_s \cdot n + \phi_0 \right) \\ \delta_n &= a_\delta \cos \left(2\pi Q_s \cdot n + \phi_0 \right) \end{aligned}$$

so long as the SYNCHROTRON TUNE

$$Q_s = \sqrt{\frac{m_s \cdot c}{2\pi} \cdot \frac{1}{\lambda_{RF}} \cdot \frac{q V_{RF}}{\beta^2 E_0}}$$

is much less than 1 !!

STANDARD MAP

Eqs. (A) + (B) are the same as the standard map

until finished {

$$\theta = \theta + \theta' \cdot \Delta t$$

$$\theta' = \theta' - \sin(\theta) \cdot \Delta t$$

}

with

1 - only 1 control parameter:

$$\cos(2\pi \cdot Q_s) = 1 - \frac{\Delta t^2}{2}$$

- Clearly something goes "wrong" when $\Delta t > 2$
- What happens Q_s becomes large?

HAMILTONIAN SHORTHAND

IF the motion of 2 variables p & q (eg. $S-z$)
can be represented by $H(p, q)$
THEN by definition

$$\frac{dq}{dt} = \frac{\partial H}{\partial p} \quad , \quad \frac{dp}{dt} = - \frac{\partial H}{\partial q}$$

so that

$$\frac{dH}{dt} = \frac{\partial H}{\partial p} \cdot \frac{dp}{dt} + \frac{\partial H}{\partial q} \cdot \frac{dq}{dt} = 0$$

and H is a constant of the motion (e.g. ENERGY)

\Rightarrow DRAW CONTOURS of H

EG GRAVITY PENDULUM

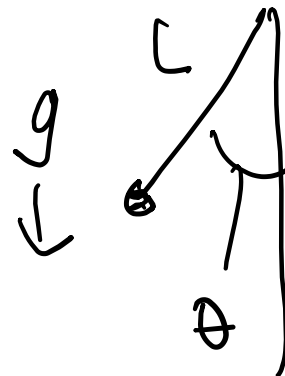
$$p \leftrightarrow \theta'$$
$$q \leftrightarrow \theta$$

$$\text{kinetic energy} \sim \frac{1}{2} L \dot{\theta}^2$$

$$\text{potential energy} \sim -g \cos(\theta)$$

So in shorthand

$$H = \frac{1}{2} \dot{\theta}^2 - \cos(\theta)$$



MOTION ALONG A CONTOUR

$$\text{VELOCITY} = \frac{dp}{dt} \hat{p} + \frac{dq}{dt} \hat{q}$$
$$= -\frac{\partial H}{\partial q} \hat{p} + \frac{\partial H}{\partial p} \hat{q}$$

\hat{p}, \hat{q}
unit vectors.

CONTOUR SLOPE

$$\vec{\nabla} H = \frac{\partial H}{\partial \vec{p}} \vec{p} + \frac{\partial H}{\partial \vec{q}} \vec{q}$$

So velocity + slope are perpendicular,
SAME LENGTH ...

⇒ SPEED is proportional to STEEPNESS

Chaos first appears near metastable equilibria

